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## Moments of Inertia

- Recall center of mass

$$\bar{x} = \frac{M_y}{M}$$

$$\bar{y} = \frac{M_x}{M}$$

$$M_y = \iint_R x \delta(x, y) dA$$

$\uparrow$  distance to  $y$ -axis

$$M_x = \iint_R y \delta(x, y) dA$$

$\uparrow$  distance to  $x$ -axis

- Moments of Inertia  $I_x, I_y$

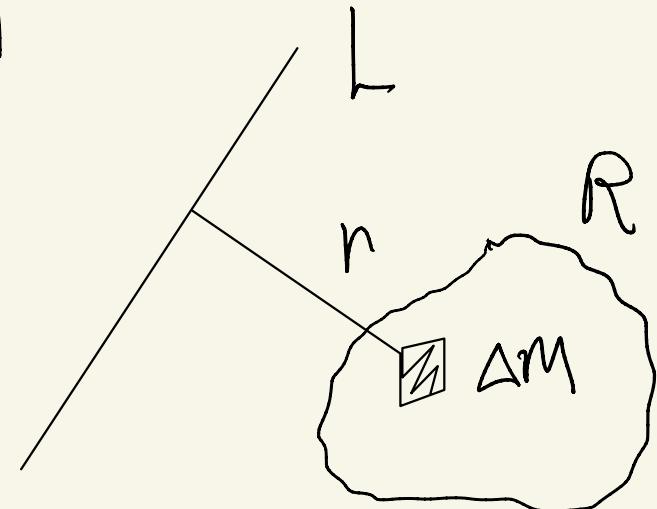
$$I_x = \iint_R y^2 \delta(x, y) dA$$

"weight the density  $\delta(x, y)$  with distance to the axis squared"

$$I_y = \iint_R x^2 \delta(x, y) dA$$

Defn: Moment of Inertia about an arbitrary axis L

$$I_L = \iint_R r^2 \delta(x, y) dA$$



Here  $r = r(x, y)$

is a function of

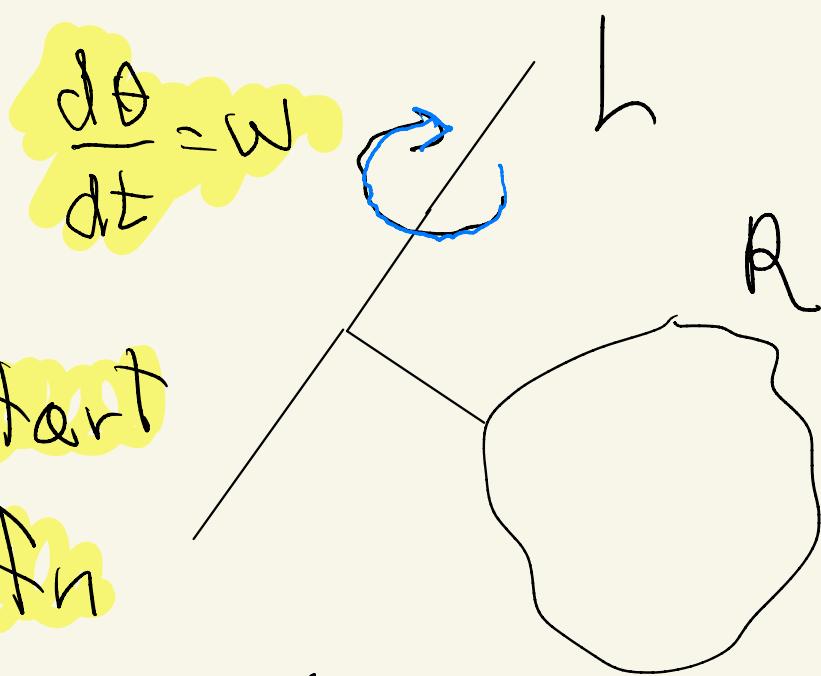
$(x, y)$  which must be computed to evaluate the integral.

Q: Why are moments of Inertia important?

Ans: (For us) Kinetic Energy of Rotation

Ex: Derive a formula for the Kinetic Energy stored in a metal plate  $R$  of density  $\delta(x,y)$  when it is rotated about axis  $L$

Picture:



Soln: We start with the defn of Kinetic Energy (KE) of a point mass  $m$ :

Defn:

$$KE = \frac{1}{2} m v^2$$

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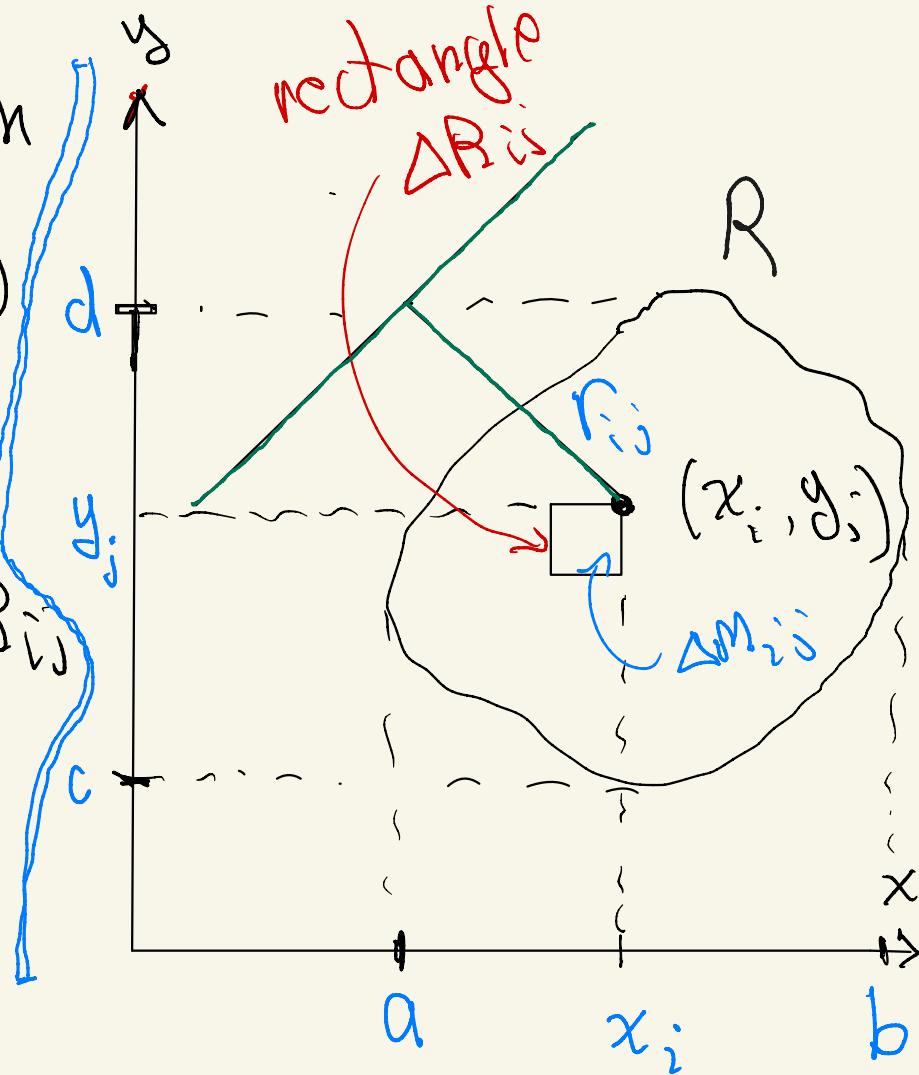
Soln: Idea: approx the KE of the continuously distributed  $\delta(x,y)$  by a Riemann Sum & take the limit to get an integral.

- Cover  $R$  with grid  $(x_i, y_j)$

- Find KE of mass  $\Delta M_{ij}$  in  $\Delta R_{ij}$

$$KE = \frac{1}{2} M V^2$$

$$M = \Delta M_{ii}$$



$$V = r_{ij} \frac{d\theta}{dt} = r_{ij} \omega$$

$$\Delta KE_{ij} = \frac{1}{2} \Delta M_{ij} (r_{ij} \omega)^2$$

$\underbrace{\Delta M}_{M}$ 
 $\underbrace{(r_{ij} \omega)^2}_{V^2}$

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$$\Delta M_{ij} \approx S(x_i, y_i) \Delta x \Delta y$$

$\frac{\text{mass}}{\text{area}} \times \text{area}$

$r_{ij}$

$\Delta M_{ij}$

$$\Delta KE_{ij} = \frac{1}{2} S(x_i, y_i) r_{ij}^2 \omega^2 \Delta x \Delta y$$

constant
constant

angular
rotation rate

$$KE = \lim_{N \rightarrow \infty} \sum_{(x_i, y_i) \in R} \left(\frac{1}{2} \omega^2\right) S(x_i, y_i) r_{ij}^2 \Delta x \Delta y$$

$$KE = \frac{1}{2} \omega^2 \iint_R r^2 S(x, y) dx dy = \frac{1}{2} I_L \omega^2$$

Conclude: The Kinetic Energy of rotation of a continuously distributed mass (metal plate) about axis L is :

$$KE = \frac{1}{2} I_L \omega^2$$

Moment of Inertia about axis L

angular rotation rate  
 $\omega = \frac{\text{radians}}{\text{sec}}$

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Example: Consider a metal

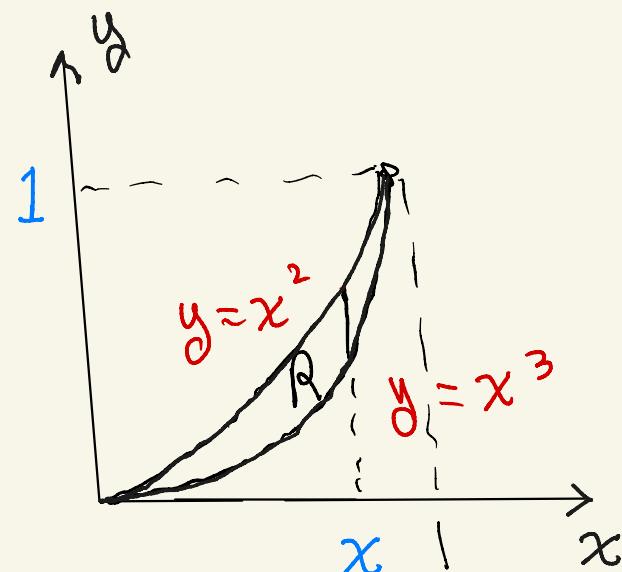
plate R of density  $\delta(x,y) = 1$   
whose shape is the region between

$$y = x^2 \text{ and } y = x^3$$

• Find the center

of mass →

$$\bar{x} = \frac{\bar{M}_y}{M}, \quad \bar{y} = \frac{\bar{M}_x}{M}$$



$$M = \iint_R \delta(x,y) dA = \iint_0^1 dy dx$$

$$= \int_0^1 y \Big|_{x^3}^{x^2} dx = \int_0^1 x^2 - x^3 dx$$

$$= \frac{x^3}{3} - \frac{x^4}{4} \Big|_0^1 = \frac{1}{3} - \frac{1}{4} = \frac{1}{12}$$

$$M = \frac{1}{12}$$

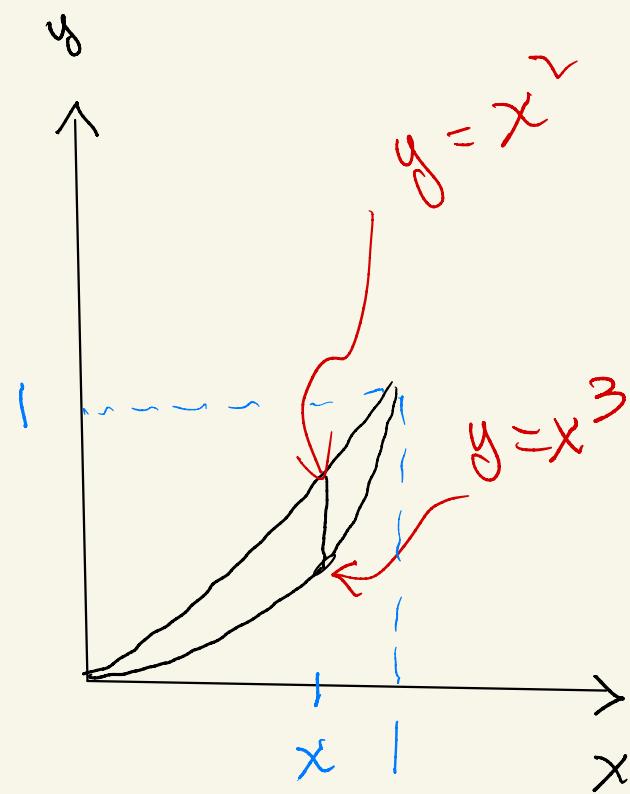
$$M_y = \iint_R x \delta(x,y) dA$$

$$= \iint_0^{x^3} x \cdot 1 dy dx$$

$$= \int_0^1 xy \Big|_{y=x^3}^{x^2} dx$$

$$= \int_0^1 x (x^2 - x^3) dx = \int_0^1 x^3 - x^4 dx$$

$$= \left[ \frac{x^4}{4} - \frac{x^5}{5} \right]_0^1 = \frac{1}{4} - \frac{1}{5} = \boxed{\frac{1}{20}}$$

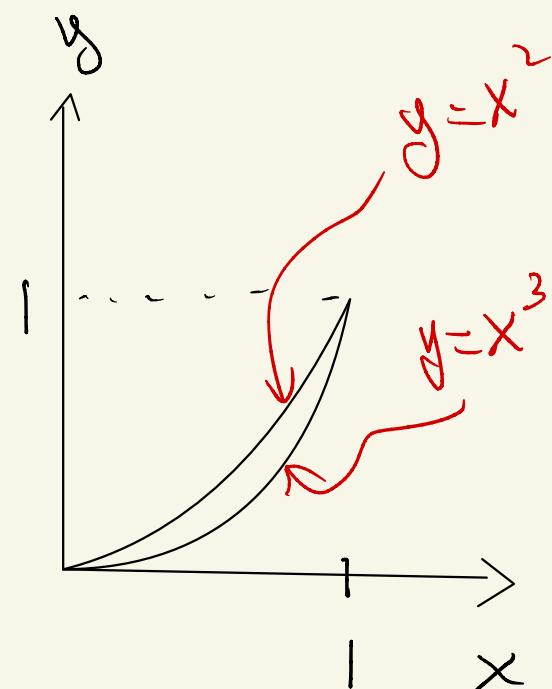


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$$M = \frac{1}{12}$$

$$M_y = \frac{1}{20}$$

$$M_x = \iint_R y \delta(x, y) dA$$



$$= \iint_R y \cdot dA$$

$$= \iint_{\substack{0 \\ x^3}}^{x^2} y dy dx = \int_0^1 \left[ \frac{y^2}{2} \right]_{x^3}^{x^2} dx$$

$$= \int_0^1 \frac{x^4}{2} - \frac{x^6}{2} dx = \left[ \frac{x^5}{10} - \frac{x^7}{14} \right]_0^1$$

$$= \frac{1}{10} - \frac{1}{14} = \frac{7}{70} - \frac{5}{70} = \frac{2}{70} = \boxed{\frac{1}{35}}$$

Conclude :  $M = \frac{1}{12}$ ,  $M_y = \frac{1}{20}$ ,  $M_x = \frac{1}{35}$  10

Thus —

$$\bar{x} = \frac{M_y}{M} = \frac{\frac{1}{20}}{\frac{1}{12}} = \frac{12}{20} = \frac{3}{5}$$

$$\bar{y} = \frac{M_x}{M} = \frac{\frac{1}{35}}{\frac{1}{12}} = \frac{12}{35}$$

Center of Mass

$$(\bar{x}, \bar{y}) = \left( \frac{3}{5}, \frac{12}{35} \right)$$

Ex: Same R and  $\delta = 1$  (11)

Find the KE of rotation of R about the y-axis, assuming a rotation rate of  $\omega$  radians/sec

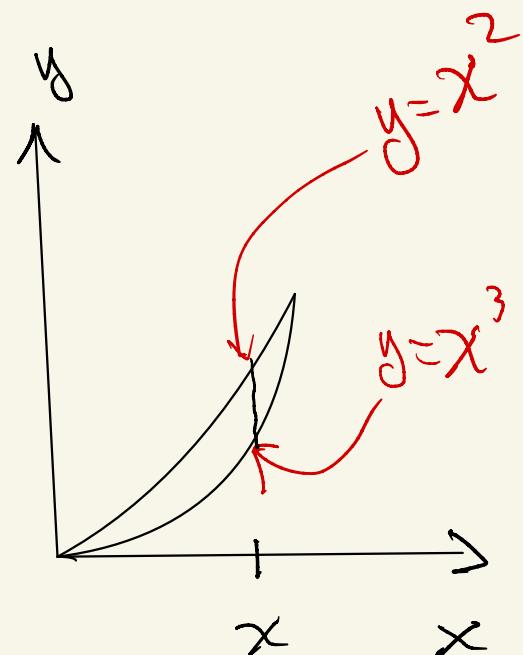
Soln:

$$KE = \frac{1}{2} I_y \omega^2 = \frac{1}{60} \omega^2$$

$$I_y = \iint x^2 \delta(x, y) dA$$

$$= \int_0^R \int_{x^3}^{x^2} x^2 dy dx = \int_0^1 x^2 y \Big|_{x^3}^{x^2} dx$$

$$= \int_0^1 x^2 (x^2 - x^3) dx = \frac{x^5}{5} - \frac{x^6}{6} \Big|_0^1 = \frac{1}{5} - \frac{1}{6} = \frac{1}{30}$$



Ex: Find the radius of gyration of  $R$  about the  $y$ -axis -

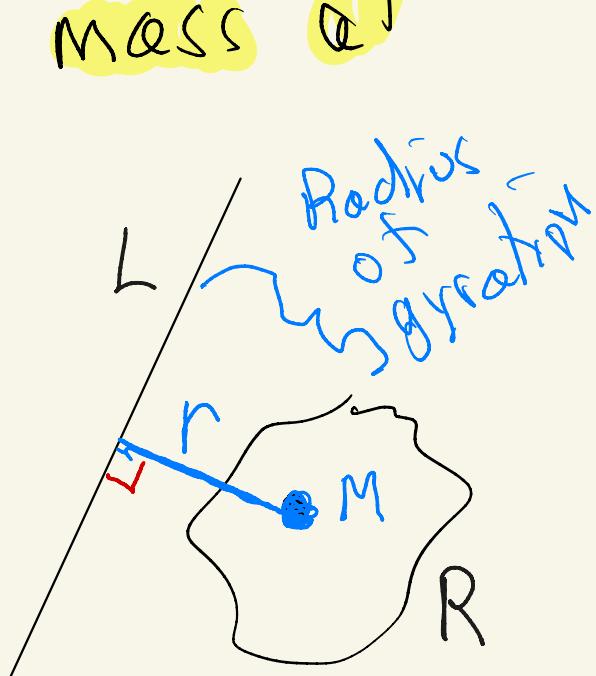
Soln. The radius of gyration is the distance from the axis at which you get the same KE of rotation with all mass at one point -

Let  $r = \text{radius of gyration}$ . Then

$$\frac{1}{2} M (r\omega)^2 = \frac{1}{2} I_L \omega^2$$

speed  
of  $M$

$$r^2 = \frac{I_L}{M} \Rightarrow$$



$$r = \sqrt{\frac{I_L}{M}}$$

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For Us : L = Length-axis

$$I_y = \frac{1}{30} M$$

$$M = \frac{1}{12}$$

$$r = \sqrt{\frac{I_y}{M}} = \sqrt{\frac{\frac{1}{30}}{\frac{1}{12}}} = \sqrt{\frac{12}{30}}$$

$$r = \sqrt{\frac{6}{15}}$$

Radius of  
gyration